

MIXED TYPE OF FUNCTIONAL EQUATION IN MATRIX NORMED SPACES

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ABSTRACT. Using the fixed point method, we establish some stability results relating to the following mixed type additive-Quadratic functional equation
 $g(-u+2v)+2[g(3u-2v)+g(2u+v)-g(v)-g(v-u)] = 3[g(u+v)+g(u-v)+g(-u)]+4g(2u-v)$
 in matrix normed spaces.

1. INTRODUCTION AND PRELIMINARIES

A basic question in the theory of functional equations is as follows: When is it true that a function, which approximately satisfies a functional equation must be close to an act solution of the equation? If the problem accepts a solution, we say the equation is stable. The first stability problem concerning group homo morphisms was raised by Ulam [23] in 1940 and affirmatively solved by Hyers [9] . The result of Hyers was generalized by Aoki [1] for approximate additive mappings and by Rassias [17] for approximate linear mappings by allowing the difference Cauchy equation $\|f(x+y) - f(x) - f(y)\|$ to be controlled by $\epsilon(\|x\|^p + \|y\|^p)$. In 1994, a generalization of the Rassias theorem was obtained by Gavruta [7] who replaced $\epsilon(\|x\|^p + \|y\|^p)$ by a general control function $\psi(x, y)$. In addition, Rassias [18]-[21] generalized the Hyers stability result by introducing two weaker conditions controlled by a product of different powers of norms and a mixed product sum of powers of norms, respectively.

The abstract characterization given for linear spaces of bounded Hilbert space operators in terms of *matricially normed spaces* [22] implies that quotients, mapping spaces and various tensor products of operator spaces may be treated as operator spaces. Owing this result, the theory of operator spaces is having a increasingly significant effect on operator algebra theory (see [5]).

The proof given in [22] appealed to the theory of ordered operator spaces [3]. Effros and Ruan [6] showed that one can give a purely metric proof of this important theorem by using a technique of Pisier [16] and Haagerup [8] (as modified in [4]).

Recently, J. R. Lee et al [13] researched the Ulam stability of Cauchy functional equation and quadratic functional equation in matrix normed spaces. This terminology may also be applied to

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the cases of other functional equations [10, 11, 12, 14, 24]. Here our purpose is to investigate to some stability result for the following equation

$$g(-u+2v)+2[g(3u-2v)+g(2u+v)-g(v)-g(v-u)] = 3[g(u+v)+g(u-v)+g(-u)]+4g(2u-v) \quad (1)$$

in matrix normed spaces by using the fixed point method.

2. GENERAL SOLUTION OF MIXED TYPE FUNCTIONAL EQUATION (1)

Lemma 1. *Let \mathcal{G} and \mathcal{H} be real vector spaces. If an odd mapping $g : \mathcal{G} \rightarrow \mathcal{H}$ satisfies (1), then g is additive.*

Proof. Suppose that g is an odd mapping, then the equation (1) is equivalent to

$$-g(u-2v)+2[g(3u-2v)+g(2u+v)-g(v)] = 3[g(u+v)-g(u)]+g(u-v)+4g(2u-v), \quad (2)$$

for all $u, v \in \mathcal{G}$. Put $u = u + v$ in (2), we obtain

$$-g(u-v)+2[g(3u+v)+g(2u+3v)-g(v)] = 3[g(u+2v)-g(u+v)]+g(u)+4g(2u+v) \quad (3)$$

for all $u, v \in \mathcal{G}$. Setting $(u, v) = (u + v, -v)$ in (3), we obtain

$$-g(u+2v)+2[g(3u+2v)+g(2u-v)+g(v)] = 3[g(u-v)-g(u)]+g(u+v)+4g(2u+v) \quad (4)$$

for all $u, v \in \mathcal{G}$. Subtracting (3) and (4), and then dividing the resulting equation by 2, one gets

$$-g(u+2v)+g(u-v)+g(2u+3v)-g(3u+2v)+g(3u+v)-g(2u-v) = -2g(u+v)+2g(u)+2g(v) \quad (5)$$

$\forall u, v \in \mathcal{G}$. Interchanging $u = v$ and $v = u$ in (5) and then adding the resulting equation to (5), one gets

$$-g(u+2v)-g(2u+v)+g(3u+v)+g(u+3v)-g(2u-v)+g(u-2v) = -4g(u+v)+4g(u)+4g(v) \quad (6)$$

Put $u = u - v$ in (6), we obtain

$$-g(u+v)-g(2u-v)+g(3u-2v)+g(u+2v)-g(2u-3v)+g(u-3v) = -4g(u)+4g(u-v)+4g(v) \quad (7)$$

for all $u, v \in \mathcal{G}$. Setting $(u, v) = (u, -v)$ in (7), we obtain

$$-g(u-v)-g(2u+v)+g(3u+2v)+g(u-2v)-g(2u+3v)+g(u+3v) = -4g(u)+4g(u+v)-4g(v) \quad (8)$$

for all $u, v \in \mathcal{G}$. Adding (7) and (8), we get

$$-g(u+2v)-g(2u+v)+g(3u+v)+g(u+3v)-g(2u-v)+g(u-2v) = -2g(u)+2g(u+v)-2g(v) \quad (9)$$

Subtracting (9) and (6), and then dividing the resulting equation by 6, one gets

$$g(u+v) = g(u) + g(v). \quad \square$$

Lemma 2. *Let \mathcal{G} and \mathcal{H} be real vector spaces. If an even mapping $g : \mathcal{G} \rightarrow \mathcal{H}$ satisfies (1), then g is quadratic.*

Proof. Suppose that g is an even mapping, then the equation (1) is equivalent to

$$g(u - 2v) + 2[g(3u - 2v) + g(2u + v) - g(v)] = 3[g(u + v) + g(u)] + 5g(u - v) + 4g(2u - v), \quad (10)$$

for all $u, v \in \mathcal{G}$. Put $u = u + v$ in (10) and $v = u + v$ in (10) and then comparing the two resulting equation, one gets

$$2g(u) + 4g(u + 2v) - 2g(2u + 3v) = -g(u + v) + 5g(u - v) + 3g(v) - g(2u + v) - 2g(u - 2v) \quad (11)$$

for all $u, v \in \mathcal{G}$. Interchanging $u = v$ and $v = u$ in (11), we obtain

$$2g(v) + 4g(2u + v) - 2g(3u + 2v) = -g(u + v) + 5g(u - v) + 3g(u) - g(u + 2v) - 2g(2u - v) \quad (12)$$

for all $u, v \in \mathcal{G}$. Put $v = -v$ in(12), we get

$$2g(v) + 4g(2u - v) - 2g(3u - 2v) = -g(u - v) + 5g(u + v) + 3g(u) - g(u - 2v) - 2g(2u + v) \quad (13)$$

Subtracting (13) and (10), and then dividing the resulting equation by 2, one gets

$$2g(v) + 4g(2u - v) - 2g(3u - 2v) = -3g(u - v) + g(u + v) \quad (14)$$

for all $u, v \in \mathcal{G}$. Setting $(u, v) = (u + v, v)$ in (14), we get

$$g(u + 2v) + 2[g(3u + v) - g(v)] = 3g(u) + 4g(2u + v), \quad (15)$$

Setting $(u, v) = (u, v - u)$ in (15), we get

$$g(-u + 2v) + 2[g(2u + v) - g(v - u)] = 3g(u) + 4g(u + v) \quad (16)$$

for all $u, v \in \mathcal{G}$. Setting $(u, v) = (u, -v)$ in (16), we obtain

$$g(u + 2v) + 2[g(2u - v) - g(u + v)] = 3g(u) + 4g(u - v) \quad (17)$$

for all $u, v \in \mathcal{G}$. Replacing u by v and v by u in (16), we obtain that

$$g(2u - v) + 2[g(u + 2v) - g(u - v)] = 3g(v) + 4g(u + v) \quad (18)$$

for all $u, v \in \mathcal{G}$. Combining (17) and (18), and then divided by 3, one gets

$$g(u + 2v) + g(2u - v) = g(u) + g(v) + 2g(u + v) + 2g(u - v) \quad (19)$$

for all $u, v \in \mathcal{G}$. Subtracting (17) from (18), and then adding the resulting equation (19), one gets

$$g(u + 2v) + g(u) = 2g(v) + 2g(u + v) \quad (20)$$

for all $u, v \in \mathcal{G}$. Setting $(u, v) = (u - v, v)$ in (20), we arrive at $g(u + v) + g(u - v) = 2g(u) + 2g(v)$. This completes the proof. \square

Throughout this paper, let $(X, \|\cdot\|_n)$ be a matrix normed space, $(Y, \|\cdot\|_n)$ be a matrix Banach space and let n be a fixed positive integer.

For a mapping $f : X \rightarrow Y$, define $\mathcal{M}f : X^2 \rightarrow Y$ and $\mathcal{M}g_n : M_n(X^2) \rightarrow M_n(Y)$ by,

$$\begin{aligned} \mathcal{M}g(p, q) &= g(-p + 2q) + 2[g(3p - 2q) + g(2p + q) - g(q) - g(q - p)] \\ &\quad - 3[g(p + q) + g(p - q) + g(-p)] - 4g(2p - q), \\ \mathcal{M}g_n([x_{ij}], [y_{ij}]) &= g([-x_{ij} + 2y_{ij}]) + 2[g([3x_{ij} - 2y_{ij}]) + g([2x_{ij} + y_{ij}]) - g([y_{ij}]) - g([y_{ij} - x_{ij}])] \\ &\quad - 3[g([x_{ij} + y_{ij}]) + g([x_{ij} - y_{ij}]) + g([-x_{ij}])] - 4g([2x_{ij} - y_{ij}]), \end{aligned}$$

for all $p, q \in X$ and all $x = [x_{ij}], y = [y_{ij}] \in M_n(X)$.

3. GENERALIZED HYERS-ULAM STABILITY OF (1): ODD CASE

Theorem 3. Let $l = \pm 1$ be fixed and let $\psi : X^2 \rightarrow [0, \infty)$ be a function such that there exists a $\tau < 1$ with

$$\psi(p, q) \leq 2^l \tau \psi\left(\frac{p}{2^l}, \frac{q}{2^l}\right) \tag{21}$$

for all $a, b \in X$. Let $g : X \rightarrow Y$ be an odd mapping satisfying $g(0) = 0$ and

$$\|\mathcal{M}f_n([x_{ij}], [y_{ij}])\| \leq \sum_{i,j=1}^n \psi(x_{ij}, y_{ij}) \quad \forall x = [x_{ij}], y = [y_{ij}] \in M_n(X). \tag{22}$$

Then there exists a unique additive mapping $\mathcal{A}_d : X \rightarrow Y$ such that

$$\|f_n([x_{ij}]) - \mathcal{A}_{dn}([x_{ij}])\|_n \leq \sum_{i,j=1}^n \frac{\tau^{\left(\frac{1-l}{2}\right)}}{2|1-\tau|} \psi(0, x_{ij}) \quad \forall x = [x_{ij}] \in M_n(X). \tag{23}$$

Proof. Put $n = 1$ in (22), we get

$$\|\mathcal{M}(p, q)\| \leq \psi(p, q) \quad \forall p, q \in X. \tag{24}$$

Letting $p = 0$ and $q = p$ in (24), we have

$$\|f(2p) - 2f(p)\| \leq \frac{1}{2} \psi(0, p) \quad \forall p \in X. \tag{25}$$

$$\text{So} \quad \left\| f(p) - \frac{1}{2^l} f(2^l p) \right\| \leq \frac{\tau^{\left(\frac{1-l}{2}\right)}}{2} \psi(0, p) \quad \forall p \in X. \tag{26}$$

Let $\mathcal{T} = \{f : X \rightarrow Y\}$ and introduce the generalized metric ρ on \mathcal{T} as follows:

$$\rho(f, g) = \inf \{ \iota \in \mathbb{R}_+ : \|f(p) - g(p)\| \leq \iota \psi(0, p), \forall p \in X \}.$$

It is easy to check that (\mathcal{T}, ρ) is a complete generalized metric (see also [15]).

Define the mapping $\mathcal{E} : \mathcal{T} \rightarrow \mathcal{T}$ by $\mathcal{E}(p) = \frac{1}{2^l} f(2^l p)$ for all $f \in \mathcal{T}$ and $p \in X$. Let $f, g \in \mathcal{T}$ and ι be an arbitrary constant with $\rho(f, g) = \iota$. Then $\|f(p) - g(p)\| \leq \iota \psi(0, p)$ for all $p \in X$. Hence

$$\|\mathcal{E}f(p) - \mathcal{E}g(p)\| = \left\| \frac{1}{2^l} f(2^l p) - \frac{1}{2^l} g(2^l p) \right\| \leq \tau \psi(0, p) \text{ for all } p \in X.$$

This means that \mathcal{E} is a contractive mapping with lipschitz constant $L = \tau < 1$.

It follows from (26) that $\rho(f, \mathcal{E}f) \leq \frac{\tau^{\left(\frac{1-l}{2}\right)}}{|2|}$. By Theorem 2.2 in [2], there exists a mapping $\mathcal{A}_d : X \rightarrow Y$ which satisfying: 1. \mathcal{A}_d is a fixed point of \mathcal{E} , i.e., $\mathcal{A}_d(2p) = 2\mathcal{A}_d(p)$

2. $\rho(\mathcal{E}^k f, \mathcal{A}_d) \rightarrow 0$ as $k \rightarrow \infty$. This implies that $\lim_{k \rightarrow \infty} \frac{1}{2^{kl}} f(2^{kl} p) = \mathcal{A}_d(p) \quad \forall p \in X$.

3. $\rho(f, \mathcal{A}_d) \leq \frac{1}{1-\tau} \rho(f, \mathcal{E} f)$, this implies the inequality

$$\|f(p) - \mathcal{A}_d(p)\| \leq \frac{\tau^{\frac{1-l}{2}}}{2|1-\tau|} \psi(0, p) \tag{27}$$

It follows from (21) and (24) that

$$\|\mathcal{M}\mathcal{A}_d(p, q)\| = \lim_{k \rightarrow \infty} \frac{1}{2^{lk}} \|\mathcal{M}f(2^{lk} p, 2^{lk} q)\| \leq \lim_{k \rightarrow \infty} \frac{1}{2^{lk}} \psi(2^{lk} p, 2^{lk} q) \leq \lim_{k \rightarrow \infty} \frac{2^{lk} \tau^k}{2^{lk}} \psi(p, q) = 0$$

Therefore

$-\mathcal{A}_d(p-2q) + 2[\mathcal{A}_d(3p-2q) + \mathcal{A}_d(2p+q) - \mathcal{A}_d(p)] - 3[\mathcal{A}_d(p+q) - \mathcal{A}_d(p)] + \mathcal{A}_d(p-q) - 4\mathcal{A}_d(2p-q) = 0$. Thus, the function \mathcal{A}_d satisfies additive. Using Lemma 2.1 in [13] and (27), we get (23). Thus $\mathcal{A}_d : X \rightarrow Y$ is a unique additive mapping. \square

Corollary 1. Let $l = \pm 1$ be fixed and let r, ς be non-negative real numbers with $r \neq 1$. Let $g : X \rightarrow Y$ be a mapping such that

$$\|\mathcal{M}f_n([x_{ij}], [y_{ij}])\|_n \leq \sum_{i,j=1}^n \varsigma(\|x_{ij}\|^r + \|y_{ij}\|^r) \quad \forall x = [x_{ij}], y = [y_{ij}] \in M_n(X). \tag{28}$$

Then there exists a unique additive mapping $\mathcal{A}_d : X \rightarrow Y$ such that

$$\|f_n([x_{ij}]) - \mathcal{A}_{dn}([x_{ij}])\|_n \leq \sum_{i,j=1}^n \frac{\varsigma}{|2-2^r|} \|x_{ij}\|^r \quad \forall x = [x_{ij}] \in M_n(X). \tag{29}$$

Proof. The proof follows from Theorem 3 by taking $\psi(p, q) = \varsigma(\|p\|^r + \|q\|^r)$ for all $p, q \in X$. Then we can choose $\tau = 2^{l(r-1)}$, and we get the desired result. \square

4. GENERALIZED HYERS-ULAM STABILITY OF (1): EVEN CASE

Theorem 4. Let $l = \pm 1$ be fixed and let $\psi : X^2 \rightarrow [0, \infty)$ be a function such that there exists a $\tau < 1$ with

$$\psi(p, q) \leq 4^l \tau \psi\left(\frac{p}{2^l}, \frac{q}{2^l}\right) \tag{30}$$

for all $p, q \in X$. Let $g : X \rightarrow Y$ be an even mapping satisfying $g(0) = 0$ and

$$\|\mathcal{M}g_n([x_{ij}], [y_{ij}])\| \leq \sum_{i,j=1}^n \psi(x_{ij}, y_{ij}) \quad \forall x = [x_{ij}], y = [y_{ij}] \in M_n(X). \tag{31}$$

Then there exists a unique quadratic mapping $\mathcal{Q}_d : X \rightarrow Y$ such that

$$\|g_n([x_{ij}]) - \mathcal{Q}_{dn}([x_{ij}])\|_n \leq \sum_{i,j=1}^n \frac{\tau^{\left(\frac{1-l}{2}\right)}}{4|1-\tau|} \psi(0, x_{ij}) \quad \forall x = [x_{ij}] \in M_n(X). \tag{32}$$

Proof. Put $n = 1$. Then (31) is equivalent to

$$\|\mathcal{M}(p, q)\| \leq \psi(p, q) \quad \forall p, q \in X. \tag{33}$$

Setting $p = 0$ and $q = p$ in (33), we get

$$\|g(2p) - 4g(p)\| \leq \frac{1}{2} \psi(0, p) \quad \forall p \in X. \tag{34}$$

$$\text{So} \quad \left\| g(p) - \frac{1}{4^l} g(2^l p) \right\| \leq \frac{\tau^{\left(\frac{1-l}{2}\right)}}{4} \psi(0, p) \quad \forall p \in X. \quad (35)$$

Let (\mathcal{T}, ρ) be the generalized metric space defined in the proof of Theorem 3. Now we consider the linear mapping $\mathcal{E} : \mathcal{T} \rightarrow \mathcal{T}$ defined by $\mathcal{E}(p) = \frac{1}{4^l} f(2^l p)$ for all $f \in \mathcal{T}$ and $p \in X$.

It follows from (35) that $\rho(f, \mathcal{E}f) \leq \frac{\tau^{\left(\frac{1-l}{2}\right)}}{|4|}$. So $\rho(f, Q_d) \leq \frac{\tau^{\frac{1-l}{2}}}{4|1-\tau|}$

The rest of the proof is similar to the proof of Theorem 3. □

Corollary 2. *Let $l = \pm 1$ be fixed and let r, ς be non-negative real numbers with $r \neq 2$. Let $g : X \rightarrow Y$ be a mapping such that*

$$\|\mathcal{M}g_n([x_{ij}], [y_{ij}])\|_n \leq \sum_{i,j=1}^n \varsigma(\|x_{ij}\|^r + \|y_{ij}\|^r) \quad \forall x = [x_{ij}], y = [y_{ij}] \in M_n(X). \quad (36)$$

Then there exists a unique quadratic mapping $\mathcal{Q}_d : X \rightarrow Y$ such that

$$\|g_n([x_{ij}]) - \mathcal{Q}_{dn}([x_{ij}])\|_n \leq \sum_{i,j=1}^n \frac{\varsigma}{|4-2^r|} \|x_{ij}\|^r \quad \forall x = [x_{ij}] \in M_n(X). \quad (37)$$

Proof. The proof follows from Theorem 4 by taking $\psi(p, q) = \varsigma(\|p\|^r + \|q\|^r)$ for all $p, q \in X$. Then we can choose $\tau = 2^{l(r-2)}$, and one can easily obtain the necessary result. □

5. J.M. RASSIAS STABILITY CONTROLLED BY THE MIXED PRODUCT-SUM OF POWERS OF NORMS

The following corollary gives the Ulam J Rassias stability for the additive-quadratic functional equation (1). This stability involving the mixed product of sum of powers of norms.

Corollary 3. *Let $l = \pm 1$ be fixed and let r, ς be non-negative real numbers with $r = v + w \neq 1$. Let $g : X \rightarrow Y$ be a mapping such that*

$$\|\mathcal{M}g_n([x_{ij}], [y_{ij}])\|_n \leq \sum_{i,j=1}^n \varsigma(\|x_{ij}\|^v \cdot \|y_{ij}\|^w + \|x_{ij}\|^{v+w} + \|y_{ij}\|^{v+w}) \quad (38)$$

for all $x = [x_{ij}], y = [y_{ij}] \in M_n(X)$. Then there exists a unique additive mapping $\mathcal{A}_d : X \rightarrow Y$ such that (29).

Proof. The proof follows from Theorem 3 by taking $\psi(p, q) = \varsigma(\|p\|^v \cdot \|q\|^w + \|p\|^{v+w} + \|q\|^{v+w})$ for all $p, q \in X$. Then we can choose $\tau = 2^{l(r-1)}$, and we can obtain the required result. □

Corollary 4. *Let $l = \pm 1$ be fixed and let r, ς be non-negative real numbers with $r = v + w \neq 2$. Let $g : X \rightarrow Y$ be a mapping such that*

$$\|\mathcal{M}g_n([x_{ij}], [y_{ij}])\|_n \leq \sum_{i,j=1}^n \varsigma(\|x_{ij}\|^v \cdot \|y_{ij}\|^w + \|x_{ij}\|^{v+w} + \|y_{ij}\|^{v+w}) \quad (39)$$

for all $x = [x_{ij}], y = [y_{ij}] \in M_n(X)$. Then there exists a unique quadratic mapping $\mathcal{Q}_d : X \rightarrow Y$ such that (37).

Proof. The proof follows from Theorem 4 by taking $\psi(p, q) = \varsigma(\|p\|^v \cdot \|q\|^w + \|p\|^{v+w} + \|q\|^{v+w})$ for all $p, q \in X$. □

6. CONCLUSION

Here, we found a general solution of a mixed type of Additive-quadratic functional equation (1) and established the generalized Hyers-Ulam stability and J. M. Rassias stability of the functional equation (1) in matrix normed spaces by using the fixed point method.

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